

# Numerical Solution of Third Order Homogenous Differential Equations Using Exponentially Fitted Collocation Method (EFCM)

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## ABSTRACT

The Exponentially Fitted Method (EFM) is an analytical and numerical method for solving various homogeneous equations. In this study, we proposed a reliable numerical method named Exponentially Fitted Collocation Method (EFCM) which will increase the rate of convergence of the initial value problems. The new method is applied to third order homogenous initial value problems. The comparative study between exact solution and Exponentially Fitted Collocation Method (EFCM) is presented. The results demonstrate liability and efficiency of the new method developed.

**Keywords:** Exponentially Fitted Collocation Method (EFCM), homogeneous equations, Initial value problems (IVP), rate of convergence, analytical and numerical solutions

## INTRODUCTION

Third order differential equations are frequently encountered in applied sciences like engineering, physics and geology. These require the determination of a function of a single independent variable satisfying a given differential equation and subject to different values at the independent variable at the initial domain. Many problems in engineering and science can be formulated as linear and non-linear differential equations e.g., Growth rate equations, Vibrational Motion, Quantum Mechanics, Steady State Condition, Heat transfer in a thin heated wire electric potential inside a thin conductor, deflection of a thin elastic thread under load and many others[1-3].

In this paper, we presented and applied a newly proposed method called Exponentially Fitted Collocation Method (EFCM) to obtain the numerical solution of the third order homogenous initial value problems of the form:

$$\frac{d^3y}{dt^3} + \alpha_1 \frac{d^2y}{dt^2} + \alpha_2 \frac{dy}{dt} + \alpha_3 y(t) + f(t, y) = g(t)$$

$$0 \leq t \leq 1 \quad (1.0)$$

Subject to the initial conditions

$$y(0) = A_1, y'(0) = A_2, y''(0) = A_3 \quad (1.1)$$

Where  $\alpha_1, \alpha_2, \alpha_3$  are coefficients of the function  $y(t)$ ,

$A_1, A_2, A_3$  are constants and  $f(t, y) = 0$

$$g(t)=0$$

The theory of collocation method has been extensively used to construct numerical solution of Ordinary Differential Equation, Taiwo O.A [4] proposed exponential fitting for the solution of two points boundary value problems with the cubic spline collocation and Tau method, Adejide and Adinira [5] proposed a five-step ninth order hybrid linear multi-step method for the solution of the first order initial value problems via the interpolation and collocation procedure and to mention just few [ see 6-10].

This paper is arranged as follows. In section 1 we briefly discussed the concept of linear equations initial value problems and the recurrence formula of the first ten shifted Chebyshev polynomials and its collocated point table is presented. In section 2, the method of the Exponentially Fitted Collocation Method (EFCM) is presented in details. In section 3, the proposed method is applied to solve some third order initial value problems and exact solutions are obtained. Finally we give a brief conclusion in the last section

## SHIFTED CHEBYSHEV POLYNOMIALS SERIES

The shifted Chebyshev polynomial is defined on the interval  $[0, 1]$  and can be determined with the aid of the

$$T_{n+1}(t) = \frac{2(2t - b - a)}{b - a} T_n(t) + T_{n-1}(t)$$

following recurrence formula.

$$T_0(t) = 1 \quad \text{and} \quad T_1(t) = 2t - 1$$

$$a \leq t \leq b,$$

Where  $a = 0, b = 1$

The first ten shifted Chebyshev are given as:

$$\begin{aligned}
T_0(t) &= 1 \\
T_1(t) &= 2t - 1 \\
T_2(t) &= 8t^2 - 8t + 1 \\
T_3(t) &= 32t^3 - 48t^2 + 18t - 1 \\
T_4(t) &= 128t^4 - 256t^3 + 160t^2 - 32t + 1 \\
T_5(t) &= 512t^5 - 1280t^4 + 1120t^3 - 400t^2 + 50t - 1 \\
T_6(t) &= 2048t^6 - 6144t^5 + 6912t^4 - 3584t^3 + 840t^2 - 72t + 1 \\
T_7(t) &= 8192t^7 - 28672t^6 + 39424t^5 - 26880t^4 + 9408t^3 - 1568t^2 + 98t - 1 \\
T_8(t) &= 32768t^8 - 131072t^7 + 212992t^6 - 180224t^5 + 84480t^4 - 21304t^3 + 2688t^2 - 128t + 1 \\
T_9(t) &= 131072t^9 - 589824t^8 + 1105920t^7 - 1118208t^6 + 658944t^5 - 228096t^4 + 44352t^3 - 4320t^2 + 162t - 1 \\
T_{10}(t) &= 524288t^{10} - 2621440t^9 + 5570560t^8 - 655360t^7 + 4659200t^6 - 2050048t^5 + 549120t^4 - 84480t^3 + 6600t^2 - 200t + 1
\end{aligned}$$

Collocate the above shifted Chebyshev polynomials at a point  $t = t_i$  and leads to Table 1

$$\text{Where } t_i = a + \frac{(b-a)i}{N+2}, i = 1, 2, 3, \dots, N+1 \quad a = 0 \quad \& \quad b = 1$$

**TABLE 1: Numerical values of Collocated First Ten Shifted Chebyshev Polynomials**

$t_i$	$N = 0$	$N = 1$	$N = 2$	$N = 3$	$N = 4$	$N = 5$
1	1	$2t_i - 1$	$8t_i^2 - 8t_i + 1$	$32t_i^3 - 48t_i^2 + 18t_i + 1$	$128t_i^4 - 256t_i^3 + 160t_i^2 - 32t_i + 1$	$512t_i^5 - 1280t_i^4 + 1120t_i^3 - 400t_i^2 + 50t_i - 1$
2	-----	0.33333333	-1.0000000	0.56800000	0.30987654	-0.79984530
3	-----	-----	-0.5000000	-0.56800000	1.00000000	-0.65692866
4	-----	-----	-----	-0.9360000	0.20987654	0.65692866
5	-----	-----	-----	-----	-0.97530864	0.79984580
6	-----	-----	-----	-----	-----	-0.74225025

$t_i$	$N = 6$	$N = 7$	$N = 8$	$N = 9$	$N = 10$
1	-0.3671875	-0.045312232	0.4219724800	-0.7177765374	0.9104895934
2	1.0000000	-0.8314009562	0.4219724800	0.0751391453	-0.5283916747
3	-0.0546875	0.6909007773	-0.9886899200	0.8935377842	-0.5000000000
4	-1.000000	0.702843568	-0.0400563200	-0.6095976872	0.9672136700
5	-0.0546875	-0.702843568	1.0000000000	-0.7306769728	0.1034987891
6	1.0000000	-0.6909007773	-0.040056320	0.7306769728	-1.0000000000
7	0.3671875	0.8314009562	-0.988689920	0.6095976872	0.1034987891
8	-----	0.045312232	0.4219724800	-0.8935377842	0.9672136700
9	-----	-----	0.4219724800	-0.0751391453	-0.5000000000
10	-----	-----	-----	0.7177765374	-0.5283916747
11	-----	-----	-----	-----	0.9104895934

## 2.0 METHODOLOGY

### DISCUSSION OF EXPONENTIALLY FITTED COLLOCATION METHOD (EFCM)

In this section, we derived a new method using power series and substituted into a slightly perturbed general third order homogenous initial value problems of the form:

$$\frac{d^3y}{dt^3} + \alpha_1 \frac{d^2y}{dt^2} + \alpha_2 \frac{dy}{dt} + \alpha_3 y(t) = 0 \quad (2.1)$$

Subject to initial conditions:

$$y(t_0) = A_1 \quad (2.2)$$

$$y'(t_0) = A_2 \quad (2.3)$$

$$y''(t_0) = A_3 \quad (2.4)$$

Where  $\alpha_1, \alpha_2, \alpha_3$  are coefficient of the function  $y(t)$

$$A_1, A_2, A_3 \in \square$$

$$t_0 = 0$$

Given an approximate solution of the form:

$$y(t) = \sum_{k=0}^N Y(k)t^k \quad (2.5)$$

Taking N as arbitrary order of the computation and obtain the third derivative of equation (2.5), we have,

$$y'(t) = \sum_{k=0}^N kY(k)t^{k-1} \quad (2.6)$$

$$y''(t) = \sum_{k=0}^N k(k-1)Y(k)t^{k-2} \quad (2.7)$$

$$y'''(t) = \sum_{k=0}^N k(k-1)(k-2)Y(k)t^{k-3} \quad (2.8)$$

Substituting equations (2.5),(2.6),(2.7) and (2.8) into equation (2.1),we obtained

$$\begin{aligned} & \sum_{k=0}^N k(k-1)(k-2)Y(k)t^{k-3} + \alpha_1 \sum_{k=0}^N k(k-1)Y(k)t^{k-2} + \alpha_2 \sum_{k=0}^N kY(k)t^{k-1} + \\ & \alpha_3 \sum_{k=0}^N Y(k)t^k = 0 \end{aligned} \quad (2.9)$$

The expansion of equation (2.9), leads to

$$\begin{aligned} & 6Y(3) + \dots + N(N-2)(N-1)Y(N)t^{N-3} + 2\alpha_1 Y(2) + 6t\alpha_1 Y(3) + \dots + \alpha_1 N(N-1)Y(N)t^{N-2} + \\ & \alpha_2 Y(1) + 2t\alpha_2 Y(2) + 3t^2\alpha_2 Y(3) + \dots + \alpha_2 NY(N)t^{N-1} + \alpha_3 Y(0) + \alpha_3 t Y(1) + \alpha_3 t^2 Y(2) + \\ & \alpha_3 t^3 Y(3) + \dots + \alpha_3 Y(N)t^N = 0 \end{aligned} \quad (2.10)$$

$$\begin{aligned} & \alpha_3 Y(0) + (\alpha_2 + \alpha_3 t)Y(1) + (2\alpha_1 + 2\alpha_2 t + \alpha_3 t^2)Y(2) + (6 + 6t\alpha_1 + 3t^2\alpha_2 + t^3\alpha_3)Y(3) + \\ & \dots + [N(N-1)(N-2)t^{N-3} + \alpha_1 N(N-1)t^{N-2} + \alpha_2 Nt^{N-1} + \alpha_3 t^N]Y(N) = 0 \end{aligned} \quad (2.11)$$

equation (2.11) and slightly perturbed to give

$$\begin{aligned} & \alpha_3 Y(0) + (\alpha_2 + \alpha_3 t)Y(1) + (2\alpha_1 + 2\alpha_2 t + \alpha_3 t^2)Y(2) + (6 + 6\alpha_1 t + 3\alpha_2 t^2 + \alpha_3 t^3)Y(3) + \dots \\ & \dots + (N(N-2)(N-1)t^{N-3} + \alpha_1 N(N-1)t^{N-2} + \alpha_2 Nt^{N-1} + \alpha_3 t^N)Y(N) = \tau_1 T_N + \tau_2 T_{N-1} \end{aligned} \quad (2.12)$$

parameters to be determined and  $T_N(t)$  and

Thus,  
collecting  
the like  
terms in

Here,  $\tau_1$  and  
 $\tau_2$  are free  
tau

$T_{N-1}(t)$  are the Chebyshev polynomials (see **Table 1**)

$$\alpha_3 Y(0) + (\alpha_2 + \alpha_3 t) Y(1) + (2\alpha_1 + 2\alpha_2 t + \alpha_3 t^2) Y(2) + (6 + 6\alpha_1 t + 3\alpha_2 t^2 + \alpha_3 t^3) Y(3) + \dots \\ \dots + [N(N-2)(N-1)t^{N-3} + \alpha_1 N(N-1)t^{N-2} + \alpha_2 Nt^{N-1} + \alpha_3 t^N] Y(N) - \tau_1 T_N - \tau_2 T_{N-1} = 0 \quad (2.13)$$

Hence, equation (2.13) gives rise to  $(N + 1)$  algebraic linear system of equations in  $(N+4)$  unknown constants. Three extra equations are obtained from the initial condition given as

$$y(t_0) = \sum_{k=0}^N Y(k)t^k + \tau_3 \ell^{t_0} = A_1 \quad (2.14)$$

$$y'(t_0) = \sum_{k=0}^N kY(k)t^{k-1} + \tau_3 \ell^{t_0} = A_2 \quad (2.15)$$

$$y''(t_0) = \sum_{k=0}^N k(K-1)Y(k)t^{k-2} + \tau_3 \ell^{t_0} = A_3 \quad (2.16)$$

Altogether, we obtained  $(N+4)$  algebraic linear equations in  $(N+4)$  unknown constants. Thus, we put the  $(N+4)$  algebraic equations in Matrix form as

$$AX = b \quad (2.17)$$

Where

$$A = \begin{pmatrix} {}^*b_{11} & {}^*b_{12} & {}^*b_{13} & \cdot & \cdot & \cdot & {}^*b_{1N} & -T_N(t_1) & -T_{N-1}(t_1) & 0 \\ {}^*b_{21} & {}^*b_{22} & {}^*b_{23} & \cdot & \cdot & \cdot & {}^*b_{2N} & -T_N(t_2) & -T_{N-1}(t_2) & 0 \\ \cdot & \cdot & \cdot & & & & \cdot & \cdot & \cdot & 0 \\ \cdot & \cdot & \cdot & & & & \cdot & \cdot & \cdot & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 2 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \end{pmatrix}$$

Here

$$\begin{aligned} {}^*b_{11} &= \left[ k(k-2)(k-1)t_1^{k-3} + \alpha_1 k(k-1)t_1^{k-2} + \alpha_2 k t_1^{k-1} + \alpha_3 t_1^k \right] \quad \text{for } k = 0 \\ {}^*b_{12} &= \left[ k(k-2)(k-1)t_1^{k-3} + \alpha_1 k(k-1)t_1^{k-2} + \alpha_2 k t_1^{k-1} + \alpha_3 t_1^k \right] \quad \text{for } k = 1 \\ {}^*b_{13} &= \left[ k(k-2)(k-1)t_1^{k-3} + \alpha_1 k(k-1)t_1^{k-2} + \alpha_2 k t_1^{k-1} + \alpha_3 t_1^k \right] \quad \text{for } k = 0 \end{aligned}$$

$$^*b_{1N} = \left[ k(k-2)(k-1)t_1^{k-3} + \alpha_1 k(k-1)t_1^{k-2} + \alpha_2 k t_1^{k-1} + \alpha_3 t_1^k \right] \quad \text{for } k = N$$

$$X = [Y(0), Y(1), Y(2), \dots, Y(N), \tau_1, \tau_2, \tau_3]^T$$

$$b = [0, 0, 0, \dots, 0, A_1, A_2, A_3]^T$$

**MAPLE 13 software** is used to obtain the unknown constant  $Y(0), Y(1), Y(2), \dots, Y(N), \tau_1, \tau_2$  and  $\tau_3$

Which are then substituted into the approximate solution

$$y(t) = \sum_{k=0}^N Y(k)t^k + \tau_3\ell^t \quad (2.18)$$

### 3.0 NUMERICAL APPLICATION

**EXAMPLE 1** Consider the third-order Homogenous initial value problem

$$\begin{aligned} & \frac{d^3y}{dt^3}(t) + 2\frac{d^2y}{dt^2} - \frac{dy}{dt} - 2y(t) = 0 \\ & 0 \leq t \leq 1 \end{aligned} \tag{3.1}$$

Subject to initial conditions

$$, \quad y(0)=1, y'(0)=0, y''(0)=0 \quad (3.2),$$

Analytical solution is give as

$$y(t) = \left[ \frac{-\ell^{-2t} + 3\ell^{-t} + \ell^t}{3} \right] \quad (3.3)$$

Consider equation (3.1), we have:

$$\alpha_1 = 2, \alpha_2 = -1 \& \alpha_3 = -2$$

$$a = 0, b = 1$$

Taking arbitrary  $N = 4$  and collocate at a point  $t = t_i$

$$\Rightarrow T_4(t) = 128t_i^4 - 256t_i^3 + 160t_i^2 - 32t_i + 1 \quad (\text{See table 1})$$

Substituting the above values into equation (2.17) leads to the matrix below.

$$\begin{bmatrix} -2.0000 & -1.3333 & 3.6111 & 7.9074 & 4.6466 & 0.9753 & -0.9360 & 0 \\ -2.0000 & -1.6667 & 3.1111 & 9.5926 & 10.4938 & -0.2099 & -0.5680 & 0 \\ -2.0000 & -2.0000 & 2.5000 & 11.0000 & 17.3750 & -1.0000 & 0.5680 & 0 \\ -2.0000 & -2.3333 & 1.7778 & 12.0747 & 25.0864 & -0.2099 & 0.9360 & 0 \\ -2.0000 & -2.6667 & 0.9444 & 12.7593 & 33.3873 & 0.9753 & 0.0000 & 0 \end{bmatrix} = \begin{bmatrix} Y(0) \\ Y(1) \\ Y(2) \\ Y(3) \\ Y(4) \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 2 & 0 & 0 & 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} \tau_1 \\ \tau_2 \\ \tau_3 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

Maple 13 software is used to obtain the unknown constants:

$$Y(0) = -1.656140560, Y(1) = -2.656140560, Y(2) = -1.328070280,$$

$$Y(3) = -0.1233568960, Y(4) = -0.2274466546,$$

$$\tau_1 = 0.02726930918, \tau_2 = 0.05579973579, \tau_3 = 2.656140560$$

These values are substituted into approximate solution given in equation (2.18):

$$y_4(t) = -1.656140560t^0 - 2.656140560t^1 - 1.328070280t^2 - 0.1233568960t^3 - 0.2274466546t^4 + 2.656140560\ell^t \quad (3.4) \text{(see table 3)}$$

**EXAMPLE 2** Consider the third-order Homogenous initial value problem

$$\frac{d^3y}{dt^3}(t) + 4\frac{d^2y}{dt^2} - \frac{dy}{dt} - 4y(t) = 0 \quad (3.5)$$

$$0 \leq t \leq 1$$

Subject to initial conditions

$$, \quad y(0) = 1, y'(0) = \sqrt{\frac{1}{3}}, y''(0) = 1 \quad (3.6),$$

Analytical solution is given as

$$y(t) = \left( \frac{3 - \sqrt{3}}{6} \right) e^{-t} + \left( \frac{\sqrt{3} + 3}{6} \right) e^t \quad (3.7)$$

Consider equation (3.5), we have:

$$\alpha_1 = 4, \alpha_2 = -1 \& \alpha_3 = -4$$

$$a = 0, b = 1$$

Taking arbitrary  $N = 4$  and collocate at a point  $t = t_i$

$$\Rightarrow T_4(t) = 128t_i^4 - 256t_i^3 + 160t_i^2 - 32t_i + 1 \quad (\text{See table 1})$$

Substituting the above values into equation (2.17) leads to the matrix below.

$$\begin{bmatrix} -4.0000 & -1.6667 & 7.5555 & 9.8981 & 5.3117 & 0.9753 & -0.9360 & 0 \\ -4.0000 & -2.3333 & 6.8889 & 13.5185 & 13.1358 & -0.2099 & -0.5680 & 0 \\ -4.0000 & -3.0000 & 6.0000 & 16.7500 & 23.2500 & -1.0000 & 0.5680 & 0 \\ -4.0000 & -3.6667 & 4.8889 & 19.4815 & 35.3580 & -0.2099 & 0.9360 & 0 \\ -4.0000 & -4.3333 & 3.5556 & 21.6019 & 49.0895 & 0.9753 & 0.0000 & 0 \end{bmatrix} \begin{bmatrix} Y(0) \\ Y(1) \\ Y(2) \\ Y(3) \\ Y(4) \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 2 & 0 & 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} \tau_1 \\ \tau_2 \\ \tau_3 \end{bmatrix} = \begin{bmatrix} 1 \\ \sqrt{\frac{1}{3}} \\ 1 \end{bmatrix}$$

Maple 13 software is used to obtain the unknown constants:

$$Y(0) = 0.2937492488, Y(1) = -0.1289004820, Y(2) = -0.1468746244,$$

$$Y(3) = -0.21192634701, Y(4) = 0.1126331034, \tau_1 = -0.0009268641178$$

$$\tau_2 = -0.001363368374, \tau_3 = 0.7062507512$$

These values are substituted into approximate solution given in equation (2.18):

$$y_4(t) = 0.2937492488t^0 - 0.1289004820t^1 - 0.1468746244t^2 - 0.2119263470t^3 + 0.1126331034t^4 + 0.7062507512\ell^t \quad (3.8)(\text{see table 4})$$

**EXAMPLE 3** Consider the third-order Homogenous initial value problem

$$\frac{d^3y}{dt^3}(t) - 2\frac{d^2y}{dt^2} + y(t) = 0 \quad (3.9)$$

$0 \leq t \leq 1$

Subject to initial conditions

$$, \quad y(0) = 1, y'(0) = 0, y''(0) = 0 \quad (3.10),$$

Analytical solution is give as

$$y(t) = \left[ \frac{\ell^t - (\sqrt{5})\ell^{\left(\frac{\sqrt{5}+1}{2}\right)t} + (\sqrt{5})\ell^{\left(\frac{-\sqrt{5}-1}{2}\right)t}}{5} \right] \quad (3.11)$$

Consider equation (3.5), we have:

$$\alpha_1 = -2, \alpha_2 = 0 \& \alpha_3 = 1$$

$$a = 0, b = 1$$

Taking arbitrary  $N = 6$  and collocate at a point  $t = t_i$

$$\Rightarrow T_6(t_i) = 2048t_i^6 - 6144t_i^5 + 6912t_i^4 - 3584t_i^3 + 840t_i^2 - 72t_i + 1 \quad (\text{See table 1})$$

Substituting the above values into equation (2.17) leads to the matrix below.

1.0000	0.1250	-3.9844	4.5020	2.6252	0.8594	0.2197	0.3672	-0.7423	0
1.0000	0.2500	-3.9375	3.0156	4.5039	3.1360	1.6409	-1.000	0.7998	0
1.0000	0.3750	-3.8594	1.5527	5.6448	6.3355	5.1444	0.0547	0.6569	0
1.0000	0.5000	-3.7500	0.1250	6.0625	10.0313	11.2656	1.0000	-0.6569	0
1.0000	0.6250	-3.6094	-1.2559	5.7776	13.7672	20.2012	0.0547	0.7998	0
1.0000	0.7500	-3.4375	-2.5781	4.8164	17.1123	31.8187	-1.0000	0.7998	0
1.0000	0.8750	-3.2344	-3.8301	3.2112	19.6535	45.6685	0.3672	0.0000	0
1	0	0	0	0	0	0	0	0	1
0	1	0	0	0	0	0	0	0	1
0	0	2	0	0	0	0	0	0	1

$$\begin{bmatrix} Y(0) \\ Y(1) \\ Y(2) \\ Y(3) \\ Y(4) \\ Y(5) \\ Y(6) \\ \tau_1 \\ \tau_2 \\ \tau_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 1 \\ 0 \\ 0 \end{bmatrix}$$

Maple 13 software is used to obtain the unknown constants:

$$Y(0) = 12.17855697, Y(1) = 11.17855697, Y(2) = 5.589278487,$$

$$Y(3) = 1.698113467, Y(4) = 0.3780143885, Y(5) = 0.6590840020$$

$$Y(6) = 0.02481151893,$$

$$\tau_1 = -0.01112829119$$

$$\tau_2 = 0.00005051496109$$

$$\tau_3 = -11.17855697$$

These values are substituted into approximate solution given in equation (2.18):

$$y_4(t) = 12.17855697t^0 + 11.17855697t^1 + 5.589278487t^2 + 0.698113467t^3 + 0.3780143885t^4 + 0.6590840020t^5 + 0.02481151893t^6 - 11.17855697\ell^t \quad (3.11) \text{(see table 5)}$$

### 3.1.0 PROBLEMS SUMMARY TABLE

**Table 2.**

parameter	Example 1	Example 2	Example 3
$\alpha_1$	2.00000	4.00000	-2.00000
$\alpha_2$	-1.00000	-1.00000	0.00000
$\alpha_3$	-2.00000	-4.00000	1.00000
$y(0)$	1.00000	1.00000	1.000000
$y'(0)$	0.00000	$\sqrt{\frac{1}{3}}$	0.00000
$y''(0)$	0.00000	1.00000	0.000000
$g(t)$	0.00000	0.000000	0.000000
<b>Nature of the function</b>	Homogenous	Homogenous	Homogenous

### 4.0 NUMERICAL SOLUTION OF EXAMPLE 1 ( EXACT AND EFCM SOLUTIONS)

**Table 3.**

t	EXACT ( $y_{exact}(t)$ )	EFCM (N=4) ( $y_{Num}(t)$ )	ERROR $ y_{exact}(t) - y_{Num}(t) $
0.0	0.9048374180	1.0000000000	0.0951625820
0.1	1.0003174730	1.0003078800	0.0000959300
0.2	1.0024249900	1.0023751530	0.0000498370
0.3	1.0078339450	1.0077327230	0.0001012220
0.4	1.0178186240	1.0176905850	0.0001280390
0.5	1.0334779360	1.0333720020	0.0001059340
0.6	1.0557864990	1.0557512770	0.0000352220
0.7	1.0856372180	1.0856954970	0.0000582790
0.8	1.1238771010	1.1240106590	0.0001335800
0.9	1.1713377340	1.1714926670	0.0001549330
1.0	1.2288616230	1.2289836660	0.0001220430

### Table 4. EXAMPLE 2 ( EXACT AND EFCM SOLUTIONS)

t	EXACT ( $y_{exact}(t)$ )	EFCM (N=4) ( $y_{Num}(t)$ )	ERROR $ y_{exact}(t) - y_{Num}(t) $
0.0	1.0000000000	1.0000000000	0.0000000000
0.1	1.0628354680	1.0628356720	0.000000204
0.2	1.1363081510	1.1363092330	0.000001082
0.3	1.2211533880	1.2211556490	0.000002261
0.4	1.3182203380	1.3182233220	0.000002984
0.5	1.4284804800	1.4284831780	0.000002698
0.6	1.5530373350	1.5530387110	0.000001376
0.7	1.6931375100	1.6931370860	0.000000424
0.8	1.8501831740	1.8501813980	0.000001776
0.9	2.0257460940	2.0257442330	0.000001861
1.0	2.2215833600	2.2215826500	0.000000710

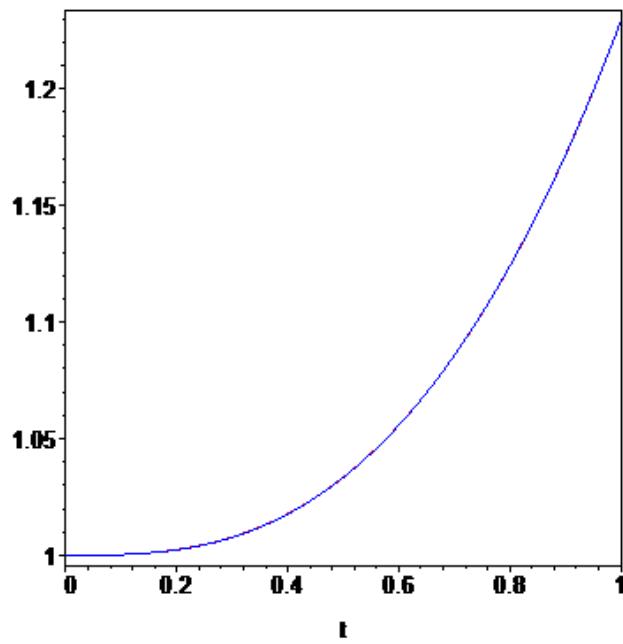
**Table 5. EXAMPLE 3 ( EXACT AND EFCM SOLUTIONS)**

t	EXACT ( $y_{exact}(t)$ )	EFCM (N=6) ( $y_{Num}(t)$ )	ERROR $ y_{exact}(t) - y_{Num}(t) $
0.0	1.000000000	1.000000000	0.000000000
0.1	0.9998246564	0.9998259500	0.000001294
0.2	0.9985220126	0.9985301700	0.000008157
0.3	0.9947363576	0.9947584800	0.000221220
0.4	0.9868145934	0.9868584300	0.000043840
0.5	0.9727440250	0.9728189100	0.000074885
0.6	0.9500784022	0.9501965600	0.000118160
0.7	0.9158004220	0.9160272500	0.000226830
0.8	0.8664654864	0.8667208000	0.000255310
0.9	0.7975816772	0.7979371100	0.000355430
1.0	0.7039590968	0.7044415700	0.000482400

**REMARKS:** **EFCM:** Exponentially Fitted Collocation Method , **EXACT:** Analytical Solutions

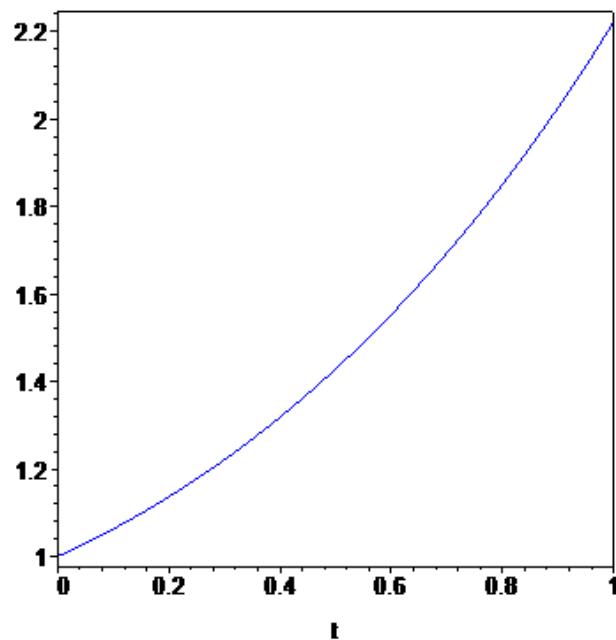
**N:** Computational length

#### EXAMPLE 1 Solution to 3RD ORDER HOMOGENOUS I.V.P



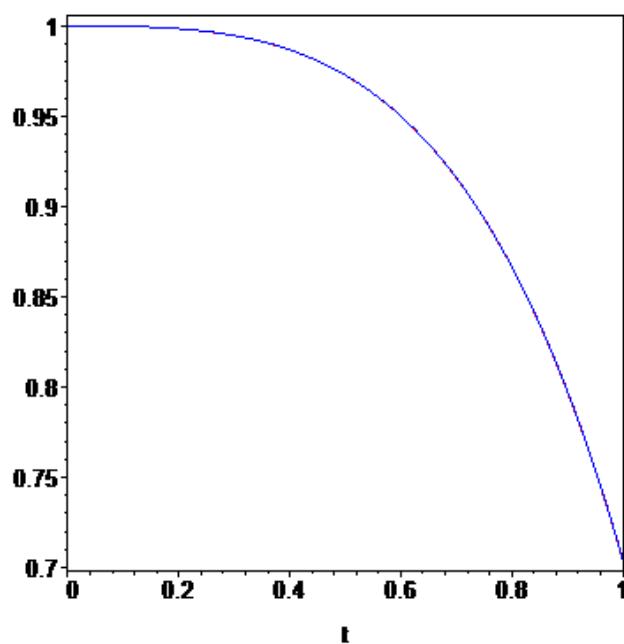
**Figure 1. (EXACT SOLUTION & EXPONENTIALLY FITTED COLLOCATION METHOD)**

**EXAMPLE 2 Solution to 3RD ORDER HOMOGENOUS I.V.P**



**Figure 2. (EXACT SOLUTION & EXPONENTIALLY FITTED COLLOCATION METHOD)**

**EXAMPLE 3 Solution to 3RD ORDER HOMOGENOUS I.V.P**



**Figure 3. (EXACT SOLUTION & EXPONENTIALLY FITTED COLLOCATION METHOD)**

**CONCLUSION**

In this paper we proposed and implemented Exponentially Fitted Collocation Method (EFCM) for solving third order linear homogenous initial value problems. The method is straightforward and very simple to apply. The numerical results by the proposed method (EFCM) show a good agreement with the exact solution. The comparisons are made between approximate solution and exact solution to illustrate the validity and the great potential of the technique. All computation in this paper is done using Maple 13 software.

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